淡江大學八十八學平度碩士班招生考試試題

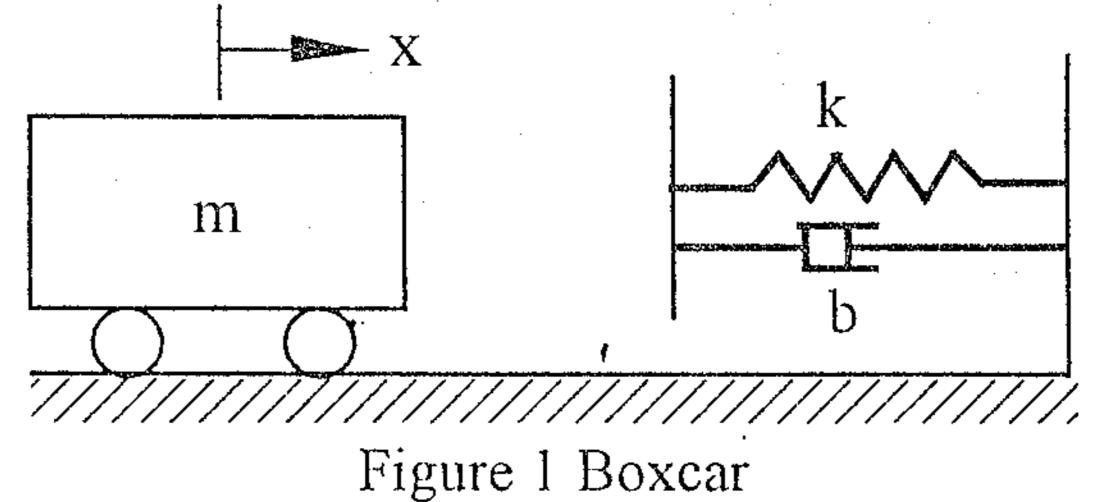
系别:機械工程學系

科目:動態系統

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(各題分數在括號內,總分為100分)

- 1. A 1000kg boxcar with a velocity 1 *m/s* approaches an arresting system composed of a linear spring and viscous damper as shown in Figure 1.
 - a. Derive the equation of motion describing what happens after the car contacts the arresting system. (10 分)
 - b. Find the time and distance when the car comes to rest. Assume that k=25N/m and b=350N sec/m. (20 分)



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2. An ideal permanent-magnet DC motor and drive system is depicted in Figure 2. Assume that the field current is constant and the inductance is negligible. The induced voltage, e_m , in the circuit and the electromechanical force(emf), T_m , can be expressed as

$$e_m = \alpha \omega$$
 $T_m = \alpha i$

where α is torque constant. The position of the motor, $\theta(t)$, is feedback by an encoder. The motor has an inertia, J, and friction coefficient B.

- a. Derive the transfer function of the motor, $\theta(s)/e_a(s)$. (10 分)
- b. Derive the transfer function of the feedback loop, $\theta(s)/\theta_i(s)$. (10 分)
- c. Adjust the amplifier gain, K_a, to get a damping ratio of 0.5 for the feedback system.

Assume that K=0.48, $\frac{\alpha}{RJ}$ =150 volt rad/sec² and $\left(\frac{B}{J} + \frac{\alpha^2}{JR}\right)$ =2.5sec. (10 分)

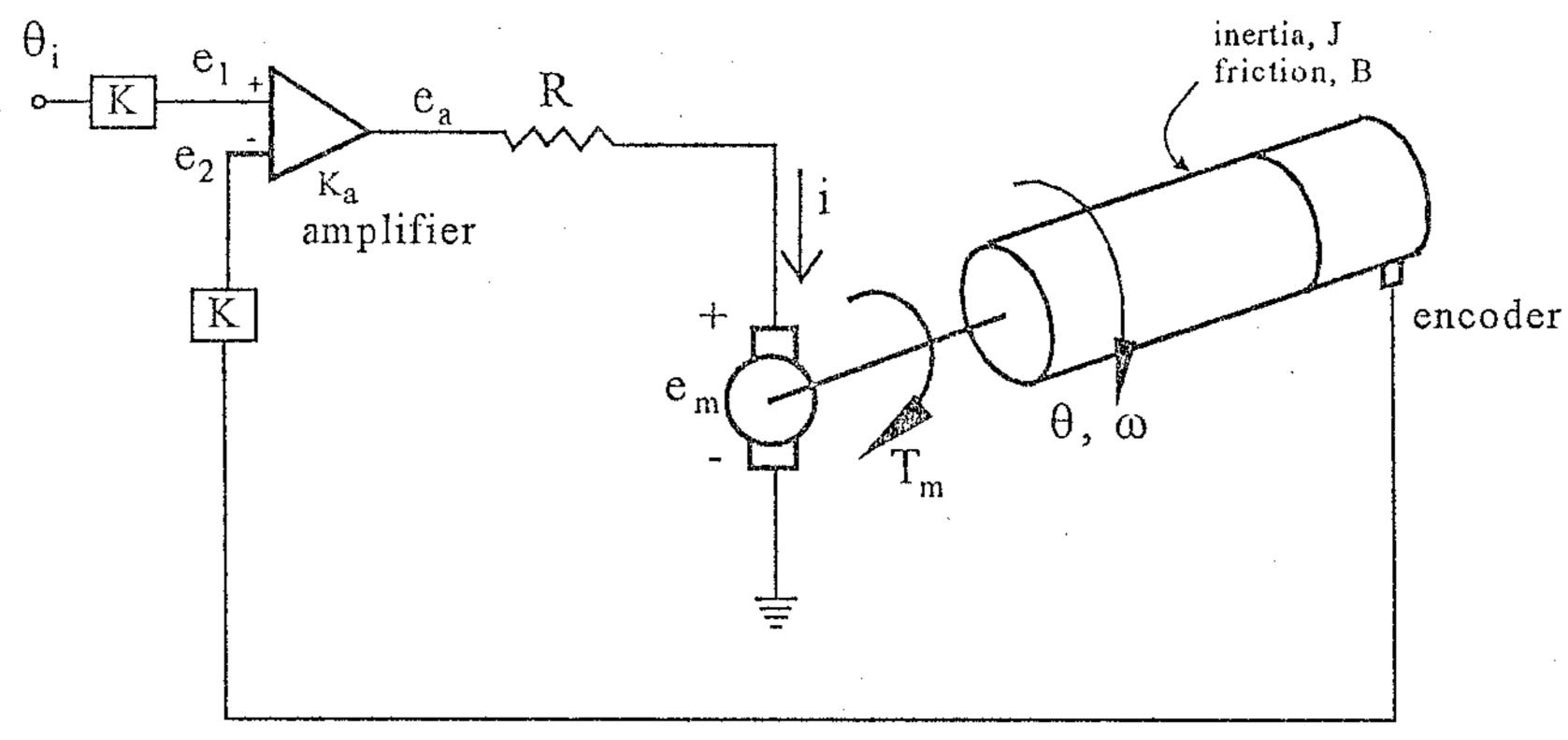


Figure 2 DC motor

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3. The disk shown in Figure 3 rolls without slipping on a horizontal plane. Attached to the disk through a frictionless hinge is a massless pendulum of length L that carries another disk. The disk at the bottom of the pendulum cannot rotate relative to the pendulum arm. Derive the equations of motion for the system. (20 分)

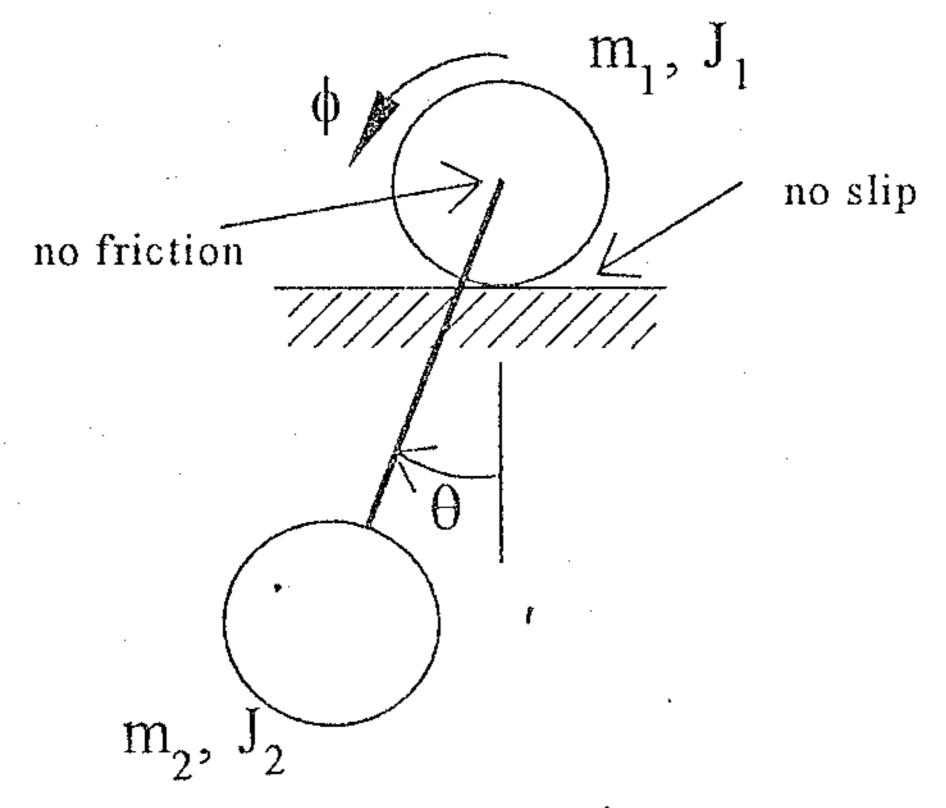


Figure 3 Rolling wheel with disk

- 4. Consider the RC circuit of Figure 4, which consists of the series connection of a voltage source, $e_s(t)$, a resistor, $R=10\Omega$, and a capacitor, C=0.1F.
 - a. Derive the dynamic system equation of the circuit. (10 分)
 - b. Determine the time constant of the system. (5 分)
 - c. If the voltage source is a step input, find the time needed for the output, $e_c(t)$, to have error less than 5%. (5 分)

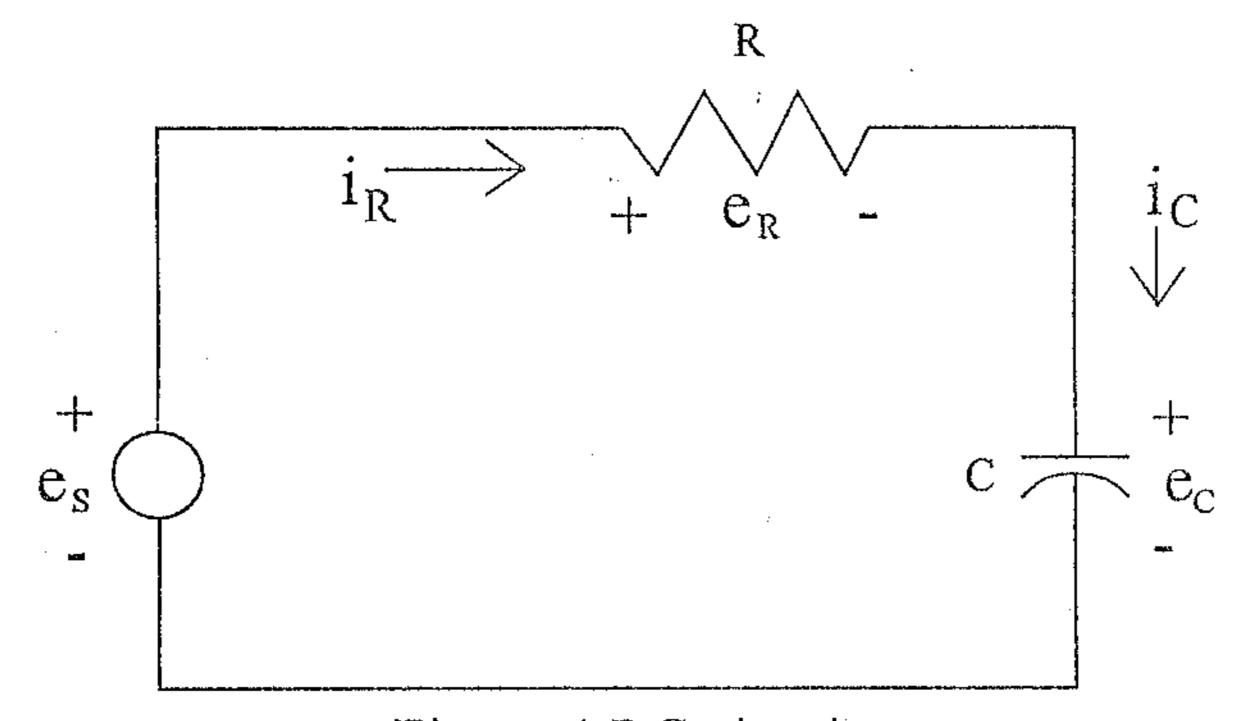


Figure 4 RC circuit